

# **JCT3V-E0142 – CE2.h related: Simplified NBDV and Improved DV derivation**

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# List of Proposed Methods

- ❖ Method 1: Simplified NBDV
- ❖ Method 2: Improved DV derivation
- ❖ Method 3: Using unavailable DV for ARP

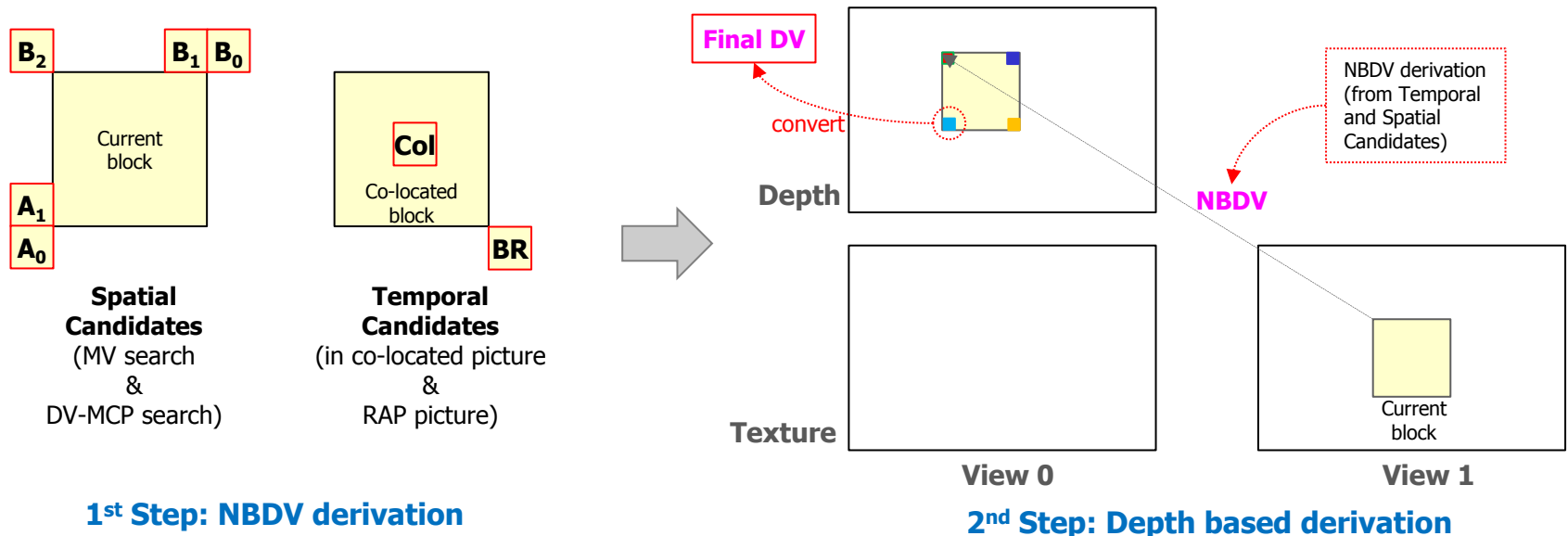
# Current DV Derivation

## ❖ 1<sup>st</sup> Step: NBDV derivation

- Temporal candidate search: BR and Col in co-located pic. and RAP pic.
- Spatial candidate search:  $A_1$ ,  $B_1$ ,  $B_0$ ,  $A_0$ , and  $B_2$
- DV-MCP:  $A_1$ ,  $B_1$ ,  $B_0$ ,  $B_1$ , and  $B_2$

## ❖ 2<sup>nd</sup> Step: Depth based derivation

- Find corresponding depth block by using **NBDV**
- Max. depth value among 4 corner pixels of the depth block → **Final DV**



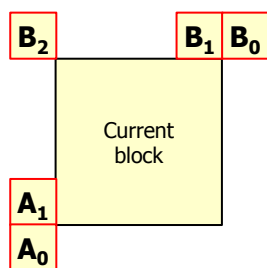
# Simplified NBDV (1)

## ❖ 1<sup>st</sup> Step: Simplified NBDV derivation

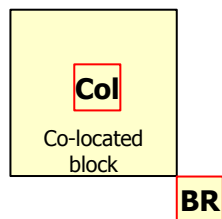
- Temporal candidate search: ~~BR~~ and Col in co-located pic. and RAP pic.
- Spatial candidate search:  $A_1$ ,  $B_1$ ,  ~~$B_0$~~ ,  ~~$A_0$~~ , and  ~~$B_2$~~
- DV-MCP:  $A_1$ ,  $B_1$ ,  ~~$B_0$~~ ,  ~~$B_{-1}$~~ , and  ~~$B_2$~~

## ❖ 2<sup>nd</sup> Step: Depth based derivation

- Find corresponding depth block by using **Simplified NBDV**
- Max. depth value among 4 corner pixels of the depth block → **Final DV**

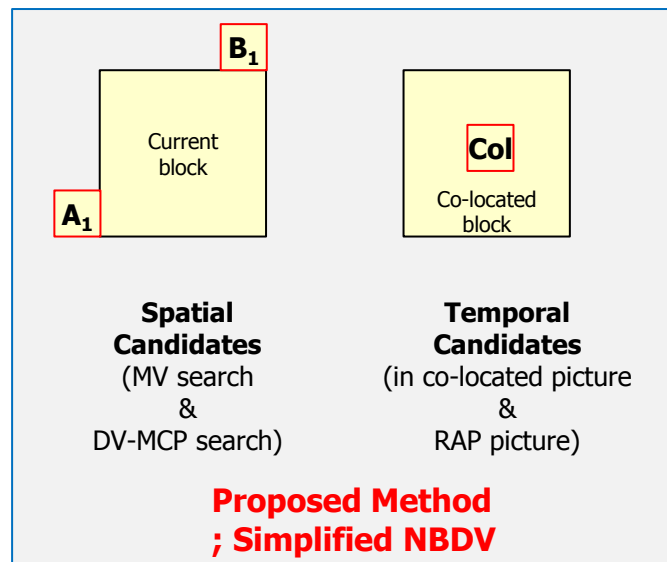
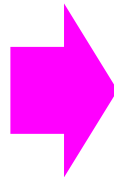


**Spatial Candidates**  
(MV search  
&  
DV-MCP search)



**Temporal Candidates**  
(in co-located picture  
&  
RAP picture)

**Current NBDV**



**Proposed Method  
; Simplified NBDV**

# Simplified NBDV (2)

## ❖ Experimental results (CTC)

- Based on HTM 7.0r1
- No coding loss  
(0.01% and 0.04% bit-saving in coded and synthesized views)

	video 0	video 1	video 2	video PSNR / video bitrate	video PSNR / total bitrate	synth PSNR / total bitrate	enc time	dec time	ren time
Balloons	0.00%	-0.03%	-0.03%	-0.02%	-0.02%	0.00%	99.7%	91.6%	98.6%
Kendo	0.00%	0.21%	-0.05%	0.04%	0.04%	0.05%	100.7%	96.4%	100.8%
Newspaper_CC	0.00%	-0.19%	-0.28%	-0.07%	-0.05%	-0.31%	100.1%	95.7%	100.0%
GT_Fly	0.00%	0.10%	-0.07%	0.00%	0.00%	0.00%	100.2%	99.1%	102.7%
Poznan_Hall2	0.00%	0.08%	0.15%	0.04%	0.04%	0.06%	100.0%	98.8%	100.8%
Poznan_Street	0.00%	-0.25%	-0.08%	-0.05%	-0.05%	-0.04%	99.4%	95.7%	100.1%
Undo_Dancer	0.00%	-0.08%	0.04%	-0.01%	-0.02%	-0.02%	99.9%	103.1%	98.9%
1024x768	0.00%	0.00%	-0.12%	-0.02%	-0.01%	-0.09%	100.2%	94.6%	99.8%
1920x1088	0.00%	-0.04%	0.01%	0.00%	-0.01%	0.00%	99.9%	99.2%	100.7%
<b>average</b>	<b>0.00%</b>	<b>-0.02%</b>	<b>-0.05%</b>	<b>-0.01%</b>	<b>-0.01%</b>	<b>-0.04%</b>	<b>100.0%</b>	<b>97.2%</b>	<b>100.3%</b>

# Simplified NBDV (3)

- ❖ Experimental results (**non-CTC; BVSP and DoNBDV off**)
  - Based on HTM 7.0r1
  - 0.15% gain in video 1
  - No coding loss  
(0.02% and 0.01% bit-saving in coded and synthesized views)

	video 0	video 1	video 2	video PSNR / video bitrate	video PSNR / total bitrate	synth PSNR / total bitrate	enc time	dec time	ren time
Balloons	0.00%	0.08%	0.31%	0.09%	0.09%	0.09%	100.2%	94.1%	101.0%
Kendo	0.00%	0.03%	0.26%	0.06%	0.05%	0.06%	99.6%	102.1%	99.0%
Newspaper_CC	0.00%	0.04%	0.01%	0.02%	-0.02%	0.02%	98.6%	100.1%	98.1%
GT_Fly	0.00%	-0.31%	-0.18%	-0.07%	-0.07%	-0.07%	100.4%	100.8%	104.5%
Poznan_Hall2	0.00%	0.05%	0.06%	0.03%	0.05%	-0.09%	98.4%	96.5%	100.9%
Poznan_Street	0.00%	-0.47%	0.01%	-0.06%	-0.05%	-0.04%	99.3%	91.0%	101.6%
Undo_Dancer	0.00%	-0.47%	-0.63%	-0.18%	-0.17%	-0.06%	100.2%	95.9%	102.4%
1024x768	0.00%	0.05%	0.19%	0.06%	0.04%	0.06%	99.5%	98.8%	99.3%
1920x1088	0.00%	-0.30%	-0.18%	-0.07%	-0.06%	-0.07%	99.6%	96.0%	102.4%
<b>average</b>	<b>0.00%</b>	<b>-0.15%</b>	<b>-0.02%</b>	<b>-0.01%</b>	<b>-0.02%</b>	<b>-0.01%</b>	<b>99.5%</b>	<b>97.2%</b>	<b>101.1%</b>

# Simplified NBDV (4)

## ❖ Complexity Analysis (CU-level) (1/2)

- Number of operations
  - Based on the current Spec.

	NBDV		Simplified NBDV	
	CTC	BVSP and DoNBDV off	CTC (ratio)	BVSP and DoNBDV off (ratio)
Comparison	260	249	112 (43%)	101 (41%)
Multiplication	3	3	1 (33%)	1 (33%)
Addition	30	16	22 (73%)	8 (50%)

# Simplified NBDV (5)

## ❖ Complexity Analysis (CU-level) (2/2)

### ■ Memory bandwidth analysis

	NBDV		Simplified NBDV	
	CTC	BVSP and DoNBDV off	CTC (ratio)	BVSP and DoNBDV off (ratio)
off-chip memory bandwidth	<b>44 bytes</b>	<b>40 bytes</b>	<b>24 bytes (55%)</b>	<b>20 bytes (50%)</b>
	<ul style="list-style-type: none"> <li>• 4 Temporal Candidates; 10 bytes * 4 = <b>40 bytes</b></li> <li>• 4 depth pixels; 1 byte * 4 = <b>4 bytes</b></li> </ul>	<ul style="list-style-type: none"> <li>• 4 Temporal Candidates; 10 bytes * 4 = <b>40 bytes</b></li> </ul>	<ul style="list-style-type: none"> <li>• 2 Temporal Candidates; 10 bytes * 2 = <b>20 bytes</b></li> <li>• 4 depth pixels; 1 byte * 4 = <b>4 bytes</b></li> </ul>	<ul style="list-style-type: none"> <li>• 2 Temporal Candidates; 10 bytes * 2 = <b>20 bytes</b></li> </ul>
on-chip memory bandwidth	<b>50 bytes</b>	<b>50 bytes</b>	<b>20 bytes (40%)</b>	<b>20 bytes (40%)</b>
	<ul style="list-style-type: none"> <li>• 5 Spatial Candidates; 10 bytes * 5 = <b>50 bytes</b></li> </ul>	<ul style="list-style-type: none"> <li>• 5 Spatial Candidates; 10 bytes * 5 = <b>50 bytes</b></li> </ul>	<ul style="list-style-type: none"> <li>• 2 Spatial Candidates; 10 bytes * 2 = <b>20 bytes</b></li> </ul>	<ul style="list-style-type: none"> <li>• 2 Spatial Candidates; 10 bytes * 2 = <b>20 bytes</b></li> </ul>
<ul style="list-style-type: none"> <li>• Accessing motion information of temporal candidate; <b>off-chip memory access</b></li> <li>• Accessing motion information of spatial candidate; <b>on-chip memory access</b></li> <li>• Size of each motion information; <b>10 bytes</b> ( ( "4-byte MV" + "1-byte ref_idx" ) * 2 (for list0 and list1) )</li> <li>• Accessing depth pixels for the depth-based derivation; <b>off-chip memory access</b></li> <li>• # of depth pixel to be accessed; <b>4 pixels</b></li> <li>• Size of depth pixel; <b>1 byte</b></li> </ul>				



# Improved DV Derivation (1)

❖ At last meeting, we proposed a depth-based 2-step DV derivation (CE2)

- 1<sup>st</sup> Step: Depth based derivation

- Find corresponding depth block by using **initial DV**

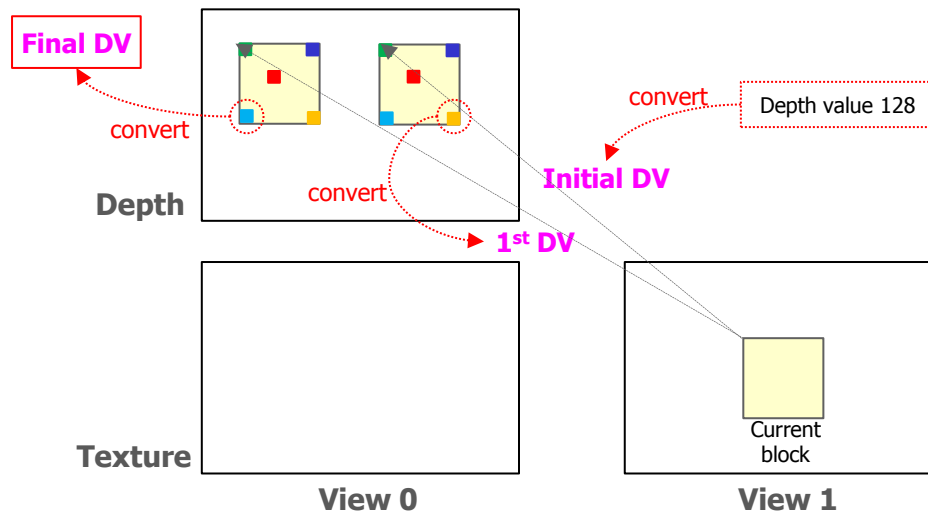
- Max. depth value → **1<sup>st</sup> DV**

set to corresponding value  
of depth value 128

- 2<sup>nd</sup> Step: Depth based derivation

- Find corresponding depth block by using **1<sup>st</sup> DV**

- Max. depth value → **Final DV**



❖ However, we observed that NBDV is suitable for ARP, which was adopted at the last meeting

# Improved DV Derivation (1)

## ❖ Therefore, we propose

- to basically use "Depth-base 2-Step DV derivation"
- to additionally use "Simplified NBDV" when the current block is coded with ARP

## ❖ Comparison of "Performed Process" and "Used DV"

- Derived DV is used for
  - Inter-view candidate derivation
  - BVSP
  - ARP

	HTM 7.0r1		Proposed Method	
	Inter-view	BVSP and ARP	Inter-view & BVSP	ARP
<b>Performed Process</b>	NBDV + DoNBDV		2-Step	2-Step + Simplified NBDV
	• DoNBDV is always needed to identify "the temporal inter-view candidate"		• NBDV is not needed to identify "the temporal inter-view candidate"	
<b>Used DV</b>	DoNBDV	NBDV	2-Step	Simplified NBDV

# Improved DV Derivation (2)

## ❖ Experimental results (CTC)

- Based on HTM 7.0r1
- 0.6% and 0.7% bit-saving for video 1 & video 2
- 0.2% and 0.1% bit-saving for coded and synthesized views

	video 0	video 1	video 2	video PSNR / video bitrate	video PSNR / total bitrate	synth PSNR / total bitrate	enc time	dec time	ren time
Balloons	0.0%	-0.4%	-0.3%	-0.1%	-0.1%	-0.1%	99.2%	89.4%	97.5%
Kendo	0.0%	-0.3%	-0.4%	-0.1%	-0.1%	-0.1%	100.2%	99.6%	100.6%
Newspaper_CC	0.0%	-0.6%	-0.9%	-0.3%	-0.2%	-0.1%	100.3%	97.0%	99.5%
GT_Fly	0.0%	-0.5%	-0.6%	-0.1%	-0.1%	-0.1%	99.9%	92.8%	102.0%
Poznan_Hall2	0.0%	-0.4%	-0.2%	-0.1%	-0.2%	-0.1%	100.3%	94.7%	100.5%
Poznan_Street	0.0%	-0.7%	-0.7%	-0.2%	-0.2%	-0.2%	99.8%	102.6%	99.8%
Undo_Dancer	0.0%	-1.0%	-1.9%	-0.4%	-0.4%	-0.2%	100.4%	100.4%	100.0%
1024x768	0.0%	-0.4%	-0.5%	-0.2%	-0.2%	-0.1%	99.9%	95.4%	99.2%
1920x1088	0.0%	-0.6%	-0.9%	-0.2%	-0.2%	-0.1%	100.1%	97.6%	100.6%
<b>average</b>	<b>0.0%</b>	<b>-0.6%</b>	<b>-0.7%</b>	<b>-0.2%</b>	<b>-0.2%</b>	<b>-0.1%</b>	<b>100.0%</b>	<b>96.7%</b>	<b>100.0%</b>

# Improved DV Derivation (3)

## ❖ Complexity Analysis (CU-level) (1/2)

- Number of operations
  - Based on the current Spec.

	DoNBDV		Improved DV derivation	
	CTC (Inter-view & BVSP)	CTC (ARP)	CTC (Inter-view & BVSP) (ratio)	CTC (ARP) (ratio)
Comparison	260	260	22 (8%)	123 (47%)
Multiplication	3	3	0 (0%)	1 (33%)
Addition	30	30	28 (93%)	36 (120%)

# Improved DV Derivation (4)

## ❖ Complexity Analysis (CU-level) (2/2)

### ■ Memory bandwidth analysis

	DoNBDV		Improved DV Derivation	
	CTC (Inter-view & BVSP)	CTC (ARP)	CTC (Inter-view & BVSP) (ratio)	CTC (ARP) (ratio)
off-chip memory bandwidth	<b>44 bytes</b>	<b>44 bytes</b>	<b>8 bytes (18%)</b>	<b>28 bytes (64%)</b>
	<ul style="list-style-type: none"> <li>• 4 Temporal Candidates; 10 bytes * 4 = <b>40 bytes</b></li> <li>• 4 depth pixels; 1 byte * 4 = <b>4 bytes</b></li> </ul>	<ul style="list-style-type: none"> <li>• 4 Temporal Candidates; 10 bytes * 4 = <b>40 bytes</b></li> <li>• 4 depth pixels; 1 byte * 4 = <b>4 bytes</b></li> </ul>	<ul style="list-style-type: none"> <li>• 8 depth pixels; 1 byte * 8 = <b>8 bytes</b></li> </ul>	<ul style="list-style-type: none"> <li>• 8 depth pixels; 1 byte * 8 = <b>8 bytes</b></li> <li>• 2 Temporal Candidates; 10 bytes * 2 = <b>20 bytes</b></li> </ul>
on-chip memory bandwidth	<b>50 bytes</b>	<b>50 bytes</b>	<b>0 bytes (0%)</b>	<b>20 bytes (40%)</b>
	<ul style="list-style-type: none"> <li>• 5 Spatial Candidates; 10 bytes * 5 = <b>50 bytes</b></li> </ul>	<ul style="list-style-type: none"> <li>• 5 Spatial Candidates; 10 bytes * 5 = <b>50 bytes</b></li> </ul>	<ul style="list-style-type: none"> <li>• N/A</li> </ul>	<ul style="list-style-type: none"> <li>• 2 Spatial Candidates; 10 bytes * 2 = <b>20 bytes</b></li> </ul>
<ul style="list-style-type: none"> <li>• Accessing motion information of temporal candidate; <b>off-chip memory access</b></li> <li>• Accessing motion information of spatial candidate; <b>on-chip memory access</b></li> <li>• Size of each motion information; <b>10 byte</b> ( ( "4-byte MV" + "1-byte ref_idx" ) * 2 (for list0 and list1) )</li> <li>• Accessing depth pixels for the depth-based derivation; <b>off-chip memory access</b></li> <li>• # of depth pixel to be accessed; <b>4 pixels</b></li> <li>• Size of depth pixel; <b>1 byte</b></li> </ul>				

# Using unavailable DV for ARP (1)

- ❖ In the current 3D-HEVC, when NBDV is unavailable, ARP is not performed
  - However, an appropriate DV can be used to allow ARP
- ❖ Therefore, we propose, when NBDV is unavailable,
  - to use the depth-based 2-step DV for ARP in case of CTC
  - to use the DV corresponding to the depth value 128 in case of non-CTC

# Using unavailable DV for ARP (2)

## ❖ Experimental results (CTC)

- Based on HTM 7.0r1
- 0.5% and 0.7% bit-saving for video 1 & video 2
- 0.2% bit-saving for coded and synthesized views

	video 0	video 1	video 2	video PSNR / video bitrate	video PSNR / total bitrate	synth PSNR / total bitrate	enc time	dec time	ren time
Balloons	0.0%	-0.5%	-0.3%	-0.2%	-0.1%	-0.1%	99.9%	90.6%	98.0%
Kendo	0.0%	-0.3%	-0.5%	-0.2%	-0.1%	-0.1%	100.1%	93.0%	98.8%
Newspaper_CC	0.0%	-0.6%	-0.9%	-0.3%	-0.2%	-0.2%	101.0%	94.2%	98.9%
GT_Fly	0.0%	-0.5%	-0.6%	-0.1%	-0.2%	-0.1%	99.4%	97.1%	100.8%
Poznan_Hall2	0.0%	-0.2%	-0.2%	0.0%	-0.1%	0.0%	100.3%	95.9%	100.7%
Poznan_Street	0.0%	-0.7%	-0.7%	-0.2%	-0.2%	-0.2%	99.8%	105.0%	101.3%
Undo_Dancer	0.0%	-1.0%	-1.9%	-0.4%	-0.4%	-0.3%	99.7%	100.2%	99.7%
1024x768	0.0%	-0.5%	-0.6%	-0.2%	-0.2%	-0.1%	100.3%	92.6%	98.5%
1920x1088	0.0%	-0.6%	-0.8%	-0.2%	-0.2%	-0.2%	99.8%	99.6%	100.6%
<b>average</b>	<b>0.0%</b>	<b>-0.5%</b>	<b>-0.7%</b>	<b>-0.2%</b>	<b>-0.2%</b>	<b>-0.2%</b>	<b>100.0%</b>	<b>96.6%</b>	<b>99.7%</b>

# Using unavailable DV for ARP (3)

## ❖ Experimental results (**non-CTC; BVSP and DoNBDV off**)

- Based on HTM 7.0r1
- 0.3% and 0.4% bit-saving for video 1 and video 2
- 0.1% bit-saving for coded and synthesized views

	video 0	video 1	video 2	video PSNR / video bitrate	video PSNR / total bitrate	synth PSNR / total bitrate	enc time	dec time	ren time
Balloons	0.0%	-0.3%	-0.5%	-0.2%	-0.2%	-0.1%	99.4%	97.6%	99.0%
Kendo	0.0%	-0.4%	-0.4%	-0.2%	-0.2%	-0.2%	99.0%	98.0%	98.8%
Newspaper_CC	0.0%	-0.8%	-0.9%	-0.3%	-0.3%	-0.3%	99.5%	104.1%	100.4%
GT_Fly	0.0%	-0.3%	0.0%	-0.1%	-0.1%	0.0%	99.6%	96.9%	103.4%
Poznan_Hall2	0.0%	0.6%	-0.4%	0.1%	0.1%	0.0%	99.0%	94.9%	98.7%
Poznan_Street	0.0%	0.0%	0.1%	0.0%	0.0%	0.0%	99.2%	89.3%	100.1%
Undo_Dancer	0.0%	-0.5%	-0.9%	-0.2%	-0.2%	-0.3%	99.5%	94.6%	102.2%
1024x768	0.0%	-0.5%	-0.6%	-0.2%	-0.2%	-0.2%	99.3%	99.9%	99.4%
1920x1088	0.0%	-0.1%	-0.3%	0.0%	0.0%	-0.1%	99.3%	93.9%	101.1%
<b>average</b>	<b>0.0%</b>	<b>-0.3%</b>	<b>-0.4%</b>	<b>-0.1%</b>	<b>-0.1%</b>	<b>-0.1%</b>	<b>99.3%</b>	<b>96.5%</b>	<b>100.4%</b>



# Conclusions

- ❖ We propose 3 methods for simplifying and improving DV derivation.
  - 0.2% bit-saving on coded and synthesized views
  - Lower complexity compared with the current DV derivation
- ❖ We recommend to adopt the proposed methods into next 3D-HEVC TM.

**Thanks to [Qualcomm](#) for the cross checking (JCT3V-E0279).**

