**Draft text changes**

In 8.4.4

….

~~– One or both of the following conditions shall be true:~~

~~– bvIntra[ 0 ] + nCbS<= 0~~

~~– bvIntra[ 1 ] + nCbS<= 0~~

In 8.4.5.2.7

….

The variable bv representing the block vector for prediction in full-sample units is derived as follows:

bv[ 0 ] = bvIntra[ 0 ] >> ( ( ( cIdx = = 0 ) ? 1 : SubWidthC ) − 1 ) (8‑63)

bv[ 1 ] = bvIntra[ 1 ] >> ( ( ( cIdx = = 0 ) ? 1 : SubHeightC ) − 1 ) (8‑64)

The (nTbS)x(nTbS) array of predicted samples samples, with x, y = 0..nTbS − 1, are derived as follows:

– The reference sample location (xRefCmp, yRefCmp ) is specified by:

( xRefCmp, yRefCmp ) = ( xTbCmp + x + bv[ 0 ], yTbCmp + y + bv[ 1 ] ) (8‑65)

If xRefCmp >= xTbCmp and yRefCmp >= yTbCmp, then (xRefCmp, yRefCmp) is modified as follows:

* If (-bv[0]) < (-bv[1])

(xRefCmp, yRefCmp) = (xRefCmp + bv[0], yTbCmp + bv[1]).

– Otherwise

(xRefCmp, yRefCmp) = (xTbCmp + bv[0], yRefCmp + bv[1]).

* Each sample at the location ( xRefCmp, yRefCmp )is assigned to predSamples[ x ][ y ].