

Merge based mvd transmission

JCTVC-F373

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1. Overview

Overview

- Proposed technique
 - Merge based mvd transmission
- Algorithm
 - Introduce merge mvd mode
 - Transmit mvd with merge predictor
 - Share the derivation process for merge mode
- Simulation results
 - Overall BD-rate gain 0.6% for RA, 1.3% for LD (with ME)
 - Overall BD-rate gain 0.2% for RA, 0.5% for LD (without ME)

2. Algorithm

Merge mvd mode

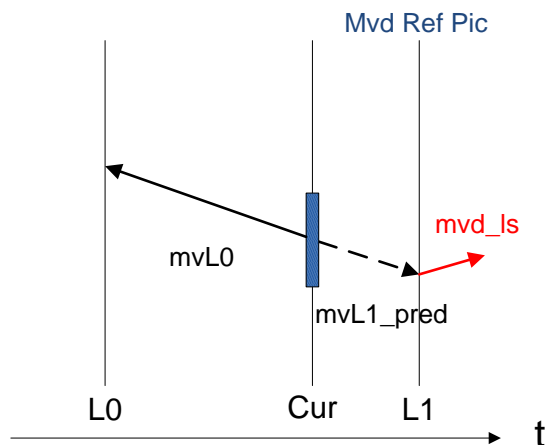
- Add new mode for inter prediction (**Merge mvd mode**)
- Transmit mvd based on merge
- Almost same decoding process with the merge mode

	Inter Pred	Merge Index	Ref Index	AMVP Index	Mvd
Merge mode	-	○ (1)	-	-	-
MergeMvd mode	○	○ (1)	-	-	○ (1)
AMVP mode	○	-	○ (1 or 2)	○ (1 or 2)	○ (1 or 2)

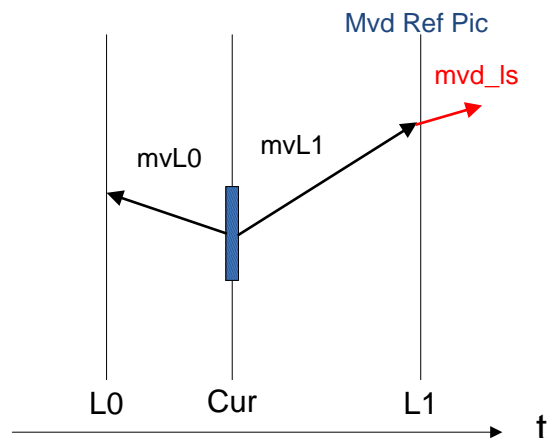
Derivation process for merge mvd mode

1. Select the reference picture to add mvd
2. (In case of uni-prediction), calculate mvp of the other list for bi-prediction
3. Calculate motion vector by adding mvd to mvp for the selected reference picture

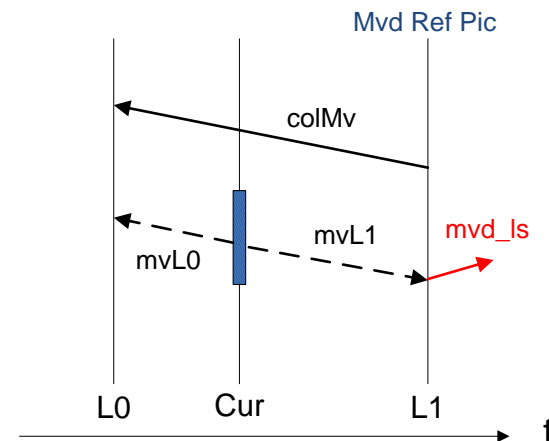
Spatial Uni-pred



Spatial Bi-pred



Temporal Bi-pred



Syntax

- Transmit 1 bit flag (merge_mvd_flag) when bi-prediction
- Transmit merge_idx and mvd_ls when merge_mvd_mode

prediction_unit(x0, y0, log2PUWidth, log2PUHeight, PartIdx , InferredMergeFlag) {	Descriptor
...	
if(slice_type == B)	
inter_pred_flag[x0][y0]	ue(v) ae(v)
...	
else { /* Inter_pred_type == Pred_BI*/	
merge_mvd_flag[x0][y0]	u(1) ae(v)
if(merge_mvd_flag[x0][y0]){	
if(NumMergeCand > 1) {	
merge_idx[x0][y0]	ue(v) ae(v)
}	
mvd_ls[x0][y0][0]	se(v) ae(v)
mvd_ls[x0][y0][1]	se(v) ae(v)
}	
...	

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3. Experiments

Simulation results **with** additional ME

- Overall BD-rate **gain 0.6% for RA, 1.3% for LD**
- 12%-17% increase of encoder runtime

	Random Access HE			Random Access LC		
	Y	U	V	Y	U	V
Class A	-0.6	-0.5	-0.5	-0.8	0.2	-0.3
Class B	-0.7	-0.6	-0.7	-0.6	-0.6	-0.6
Class C	-0.6	-0.5	-0.5	-0.4	-0.5	-0.4
Class D	-0.7	-0.5	-0.5	-0.5	-0.6	-0.5
Class E						
Overall	-0.6	-0.5	-0.6	-0.6	-0.4	-0.5
Enc Time[%]	114%			117%		
Dec Time[%]	101%			100%		

	Low delay B HE			Low delay B LC		
	Y	U	V	Y	U	V
Class A						
Class B	-1.1	-1.7	-1.7	-1.7	-1.9	-1.7
Class C	-1.2	-1.2	-1.3	-1.2	-1.0	-1.1
Class D	-1.1	-1.0	-0.5	-0.9	-0.8	-1.1
Class E	-1.3	-1.5	-2.2	-1.9	-3.0	-2.0
Overall	-1.2	-1.4	-1.4	-1.4	-1.6	-1.5
Enc Time[%]	112%			114%		
Dec Time[%]	101%			101%		

Simulation results **without** additional ME

- Overall BD-rate **gain 0.1-0.2% for RA, 0.4-0.5% for LD**
- 3%-4% increase of encoder runtime

	Random Access HE			Random Access LC		
	Y	U	V	Y	U	V
Class A	-0.2	-0.2	-0.2	-0.2	-0.1	-0.3
Class B	-0.2	-0.2	-0.2	-0.1	-0.1	-0.1
Class C	-0.2	-0.2	-0.2	-0.1	-0.1	0.0
Class D	-0.2	-0.2	-0.2	-0.1	-0.2	-0.2
Class E						
Overall	-0.2	-0.2	-0.2	-0.1	-0.2	-0.2
Enc Time[%]	104%			104%		
Dec Time[%]	100%			99%		

	Low delay B HE			Low delay B LC		
	Y	U	V	Y	U	V
Class A						
Class B	-0.3	-0.6	-1.0	-0.6	-0.6	-0.6
Class C	-0.4	-0.4	-0.4	-0.4	-0.4	-0.4
Class D	-0.4	-0.5	0.1	-0.3	-0.3	-0.4
Class E	-0.4	-0.3	-0.6	-0.9	-0.6	-0.4
Overall	-0.4	-0.5	-0.5	-0.5	-0.5	-0.5
Enc Time[%]	103%			103%		
Dec Time[%]	101%			100%		

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4. Conclusion

Conclusion

- Suggestion
 - Further investigated in CE

- Future work
 - Non-normative algorithm for low complexity encoder
 - How to add mvd to mvp
 - Syntax position of the merge mvd mode

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HOLDINGS

The logo graphic consists of two parallel, curved, grey swooshes that originate from the right side of the word 'HOLDINGS' and extend upwards and to the right, ending near the top right of the frame.